

## 2.2 SOLUTIONS

14. On the set  $\{(a, b)\}$  of all ordered pairs of positive integers, define  $(x_1, y_1) \sim (x_2, y_2)$  if  $x_1 y_2 = x_2 y_1$ . Show that this defines an equivalence relation.

*Solution:* We first show that the reflexive law holds. Given an ordered pair  $(a, b)$ , we have  $ab = ba$ , and so  $(a, b) \sim (a, b)$ .

We next check the symmetric law. Given  $(a_1, b_1)$  and  $(a_2, b_2)$  with  $(a_1, b_1) \sim (a_2, b_2)$ , we have  $a_1 b_2 = a_2 b_1$ , and so  $a_2 b_1 = a_1 b_2$ , which shows that  $(a_2, b_2) \sim (a_1, b_1)$ .

Finally, we verify the transitive law. Given  $(a_1, b_1)$ ,  $(a_2, b_2)$ , and  $(a_3, b_3)$  with  $(a_1, b_1) \sim (a_2, b_2)$  and  $(a_2, b_2) \sim (a_3, b_3)$ , we have the equations  $a_1 b_2 = a_2 b_1$  and  $a_2 b_3 = a_3 b_2$ . If we multiply the first equation by  $b_3$  and the second equation by  $b_1$ , we get  $a_1 b_2 b_3 = a_2 b_1 b_3 = a_3 b_1 b_2$ . Since  $b_2 \neq 0$  we can cancel to obtain  $a_1 b_3 = a_3 b_1$ , showing that  $(a_1, b_1) \sim (a_3, b_3)$ .

15. On the set  $\mathbf{C}$  of complex numbers, define  $z_1 \sim z_2$  if  $\|z_1\| = \|z_2\|$ . Show that  $\sim$  is an equivalence relation.

*Solution:* The reflexive, symmetric, and transitive laws can be easily verified since  $\sim$  is defined in terms of an equality, and equality is itself an equivalence relation.

16. Let  $\mathbf{u}$  be a fixed vector in  $\mathbf{R}^3$ , and assume that  $\mathbf{u}$  has length 1. For vectors  $\mathbf{v}$  and  $\mathbf{w}$ , define  $\mathbf{v} \sim \mathbf{w}$  if  $\mathbf{v} \cdot \mathbf{u} = \mathbf{w} \cdot \mathbf{u}$ , where  $\cdot$  denotes the standard dot product. Show that  $\sim$  is an equivalence relation, and give a geometric description of the equivalence classes of  $\sim$ .

*Solution:* The reflexive, symmetric, and transitive laws for the relation  $\sim$  really depend on an equality, and can easily be verified. Since  $\mathbf{u}$  has length 1,  $\mathbf{v} \cdot \mathbf{u}$  represents the length of the projection of  $\mathbf{v}$  onto the line determined by  $\mathbf{u}$ . Thus two vectors are equivalent if and only if they lie in the same plane perpendicular to  $\mathbf{u}$ . It follows that the equivalence classes of  $\sim$  are the planes in  $\mathbf{R}^3$  that are perpendicular to  $\mathbf{u}$ .

17. For the function  $f : \mathbf{R} \rightarrow \mathbf{R}$  defined by  $f(x) = x^2$ , for all  $x \in \mathbf{R}$ , describe the equivalence relation on  $\mathbf{R}$  that is determined by  $f$ .

*Solution:* The equivalence relation determined by  $f$  is defined by setting  $a \sim b$  if  $f(a) = f(b)$ , so  $a \sim b$  if and only if  $a^2 = b^2$ , or,  $a \sim b$  if and only if  $|a| = |b|$ .

18. For the linear transformation  $L : \mathbf{R}^3 \rightarrow \mathbf{R}^3$  defined by

$$L(x, y, z) = (x + y + z, x + y + z, x + y + z),$$

for all  $(x, y, z) \in \mathbf{R}^3$ , give a geometric description of the partition of  $\mathbf{R}^3$  that is determined by  $L$ .

*Solution:* Since  $(a_1, a_2, a_3) \sim (b_1, b_2, b_3)$  if  $L(a_1, a_2, a_3) = L(b_1, b_2, b_3)$ , it follows from the definition of  $L$  that  $(a_1, a_2, a_3) \sim (b_1, b_2, b_3)$  if and only if  $a_1 + a_2 + a_3 = b_1 + b_2 + b_3$ . For example,  $\{(x, y, z) \mid L(x, y, z) = (0, 0, 0)\}$  is the plane through the origin whose equation is  $x + y + z = 0$ , with normal vector  $(1, 1, 1)$ . The other subsets in the partition of  $\mathbf{R}^3$  defined by  $L$  are planes parallel to this one. Thus the partition consists of the planes perpendicular to the vector  $(1, 1, 1)$ .

19. Define the formula  $f : \mathbf{Z}_{12} \rightarrow \mathbf{Z}_{12}$  by  $f([x]_{12}) = [x]_{12}^2$ , for all  $[x]_{12} \in \mathbf{Z}_{12}$ . Show that the formula  $f$  defines a function. Find the image of  $f$  and the set  $\mathbf{Z}_{12}/f$  of equivalence classes determined by  $f$ .

*Solution:* The formula for  $f$  is well-defined since if  $[x_1]_{12} = [x_2]_{12}$ , then  $x_1 \equiv x_2 \pmod{12}$ , and so  $x_1^2 \equiv x_2^2 \pmod{12}$ , which shows that  $f([x_1]_{12}) = f([x_2]_{12})$ .

To compute the images of  $f$  we have  $[0]_{12}^2 = [0]_{12}$ ,  $[\pm 1]_{12}^2 = [1]_{12}$ ,  $[\pm 2]_{12}^2 = [4]_{12}$ ,  $[\pm 3]_{12}^2 = [9]_{12}$ ,  $[\pm 4]_{12}^2 = [4]_{12}$ ,  $[\pm 5]_{12}^2 = [1]_{12}$ , and  $[6]_{12}^2 = [0]_{12}$ . Thus  $f(\mathbf{Z}_{12}) = \{[0]_{12}, [1]_{12}, [4]_{12}, [9]_{12}\}$ . The corresponding equivalence classes determined by  $f$  are  $\{[0]_{12}, [6]_{12}\}$ ,  $\{[\pm 1]_{12}, [\pm 5]_{12}\}$ ,  $\{[\pm 2]_{12}, [\pm 4]_{12}\}$ ,  $\{[\pm 3]_{12}\}$ .

20. On the set of all  $n \times n$  matrices over  $\mathbf{R}$ , define  $A \sim B$  if there exists an invertible matrix  $P$  such that  $PAP^{-1} = B$ . Check that  $\sim$  defines an equivalence relation.

*Solution:* We have  $A \sim A$  since  $IAI^{-1} = A$ , where  $I$  is the  $n \times n$  identity matrix. If  $A \sim B$ , then  $PAP^{-1} = B$  for some invertible matrix  $P$ , and so we get  $A = P^{-1}B(P^{-1})^{-1}$ . If  $A \sim B$  and  $B \sim C$ , then  $PAP^{-1} = B$  and  $QBQ^{-1} = C$  for some  $P, Q$ . Substituting gives  $Q(PAP^{-1})Q^{-1} = (QP)A(QP)^{-1} = C$ , and so  $A \sim C$ .