

MATH 434 / 534 (EXAM 2)

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Note: Each problem carries 20 points.

1. (a) Show that the matrix

$$A = \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & 0 \\ -1 & 0 & 4 \end{pmatrix}$$

is both **diagonally dominant** and **symmetric positive definite**.

In order to show that A is diagonally dominant,

$$4 > |-1| + |-1| = 2$$

$$4 > |-1| + |0| = 1$$

$$4 > |0| + |-1| = 1.$$

$\Rightarrow A$ diagonally dominant.

To show that A is symmetric positive definite, check the determinant of each leading submatrix is positive. The leading principle minors are 4, 15, and 56.

- (b) Find the **Cholesky factorization** of A .

$$h_{11} = \sqrt{a_{11}} = 2.$$

$$h_{21} = \frac{a_{21}}{h_{11}} = -0.5.$$

$$h_{22} = \sqrt{a_{22} - h_{21}^2} = 1.9365.$$

$$h_{31} = \frac{a_{31}}{h_{11}} = -0.5.$$

$$h_{32} = \frac{a_{32} - h_{21}h_{31}}{h_{22}} = -0.1291.$$

$$h_{33} = \sqrt{a_{33} - h_{31}^2 - h_{32}^2} = 1.9322.$$

$$H = \begin{pmatrix} 2 & 0 & 0 \\ -0.5 & 1.9365 & 0 \\ -0.5 & -0.1291 & 1.9322 \end{pmatrix}$$

(c) Using **the Cholesky factorization**, solve the system:

$$Ax = \begin{pmatrix} 2 \\ 3 \\ 3 \end{pmatrix}.$$

$$x = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}.$$

Step 1:

$$\begin{aligned} A &= HH^T \\ Ax &= HH^T x = b \end{aligned}$$

Step 2:

$$Hy = b$$

Step 3:

$$H^T x = y = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

(d) Compute $\det(A)$ **from the Cholesky factorization**. [No credit will be given if you do otherwise.]

Since a matrix A is decomposed as $A = HH^T$ and H is a triangular matrix

$$\begin{aligned} \det(A) &= \det(H) \det(H^T) \\ &= \det(H) \det(H) = 56 \end{aligned}$$

2. (a) Describe an algorithm to compute a Householder matrix H such that

$$H \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} * \\ 0 \\ 0 \end{pmatrix}$$

$$u = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + \sqrt{2} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \sqrt{2} \\ 1 \\ 1 \end{pmatrix}$$

$$H = I - 2 \frac{uu^T}{u^T u} = \begin{pmatrix} 0 & -0.7071 & -0.7071 \\ -0.7071 & 0.5 & -0.5 \\ -0.7071 & -0.5 & 0.5 \end{pmatrix}$$

Then we have

$$H \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1.442 \\ 0 \\ 0 \end{pmatrix}.$$

(b) Using Householder's method, find the QR factorization of

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 2 \\ 1 & 3 \end{pmatrix}$$

Step 1.

$$H_1 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} * \\ 0 \\ 0 \end{pmatrix}$$

$$H_1 = \begin{pmatrix} 0 & -0.7071 & -0.7071 \\ -0.7071 & 0.5 & -0.5 \\ -0.7071 & -0.5 & 0.5 \end{pmatrix}$$

$$H_1 A = A^{(1)} = \begin{pmatrix} -1.4142 & -3.5355 \\ 0 & -1.2071 \\ 0 & -0.2071 \end{pmatrix}$$

Step 2.

$$\widehat{H}_2 \begin{pmatrix} -1.2071 \\ -0.2071 \end{pmatrix} = \begin{pmatrix} \star \\ 0 \end{pmatrix}$$

$$\widehat{u}_2 = \begin{pmatrix} -1.2071 \\ -0.2071 \end{pmatrix} - \left\| \begin{pmatrix} -1.2071 \\ -0.2071 \end{pmatrix} \right\| e_1$$

$$\widehat{H}_2 = \begin{pmatrix} -0.9856 & -0.1691 \\ -0.1691 & 0.9856 \end{pmatrix}$$

Step 3.

$$H_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \widehat{H}_2(1,1) & \widehat{H}_2(1,2) \\ 0 & \widehat{H}_2(2,1) & \widehat{H}_2(2,2) \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -0.9856 & -0.1691 \\ 0 & -0.1691 & 0.9856 \end{pmatrix}$$

$$Q = H_1 H_2 = \begin{pmatrix} 0 & 0.8165 & -0.5774 \\ -0.7071 & -0.4082 & -0.5774 \\ -0.7071 & 0.4082 & 0.5774 \end{pmatrix}$$

Step 4.

$$R = H_2 H_1 A = \begin{pmatrix} -1.4142 & -3.5355 \\ 0 & 1.2297 \\ 0 & 0 \end{pmatrix}$$

(c) Find the least-square solution to: $Ax = \begin{pmatrix} 1 \\ 3 \\ 4 \end{pmatrix}$ using the QR factorization.

Step 1.

$$QRx = b \text{ or } Rx = Q^T b = c$$

$$Rx = \begin{pmatrix} -4.9497 \\ 1.2247 \\ 0 \end{pmatrix}$$

Step 2.

$$Rx = c \text{ for } x,$$

we have $x = (1, 1)^T$

3. (a) State a mathematical result that shows that solving least-squares problem by QR factorization is a stable process.

Computed solution \hat{x} is such that it minimizes $\|(A + E)\hat{x} - (b + \delta b)\|_2$, where E and δb are small. Specially,

$$\begin{aligned}\|E\|_F &\leq c\mu n\|A\|_F + O(\mu^2) \\ \|\delta b\|_2 &\leq c\mu\|b\|_2 + O(\mu^2)\end{aligned}$$

where $c \approx 6m - 3n + 41$ and μ is the machine precision.

- (b) State a **mathematical result** that shows that Householder's method for QR factorization is stable.

If \hat{R} denotes the computed R , then \exists an orthogonal \hat{Q} such that $A + E = \hat{Q}\hat{R}$. The error matrix E satisfies $\|E\|_F \leq \phi(n)\mu\|A\|_F$ where $\phi(n)$ is a slowly growing function of n and μ is the machine precision.

4. Given

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

- (a) Find the singular values and singular vectors of A .

SVD of A :

$$U = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \quad \Sigma = \begin{pmatrix} 2 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \quad \text{and} \quad V^T = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Left Singular Vectors : $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$, $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, and $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$.

Right Singular Vectors : $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$.

- (b) Find $\|A\|_2$, $\|A\|_F$, $Cond_2(A)$, **using the singular values of A .**

$$\begin{aligned}\|A\|_2 &= \sigma_{\max} = 2. \\ \|A\|_F &= \sqrt{\sigma_1^2 + \sigma_2^2} = \sqrt{5}. \\ cond_2(A) &= \frac{\sigma_{\max}}{\sigma_{\min}} = \frac{2}{1} = 2.\end{aligned}$$

- (c) Find the least-squares solution to $Ax = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$, using the singular value decomposition of A .

Step 1. Deleting the last column of U and last row of Σ , we obtained a truncated SVD of A as follows :

$$\bar{U}_1 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \\ 1 & 0 \end{pmatrix} \quad \Sigma_1 = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad V_1^T = V_1^T = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Step 2.

$$b' = \bar{U}_1^T b = \begin{pmatrix} 0 & 1 \\ 0 & 0 \\ 1 & 0 \end{pmatrix}^T \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Step 3.

$$\begin{aligned} \Sigma_1 y &= b' \\ \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} &= \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ y_1 &= \frac{1}{2}, \quad y_2 = 1. \end{aligned}$$

Step 4.

$$x = V_1 y = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ \frac{1}{2} \end{pmatrix}$$

- (d) Construct an example of an 3×2 matrix which is of full rank (theoretically) but close to a rank-deficient matrix.

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 10^{-4} \\ 0 & 0 \end{pmatrix}$$

5. Prove the following results:

(a) $\|A^T A\|_2 = \|A\|_2^2$

$$A = \bar{U}\Sigma V^T \rightarrow \|A\|_2 = \sigma_{\max} = \sigma_1 \dots \mathbf{1}$$

$$A^T = V\Sigma\bar{U}^T$$

$$\text{So, } A^T A = \bar{U}\Sigma^T V V^T \Sigma \bar{U} = \bar{U}\Sigma\Sigma^T \bar{U}^T.$$

$$\text{Since } \Sigma\Sigma^T = \text{diag}(\sigma_1^2, \sigma_2^2, \dots, \sigma_n^2),$$

$$\|A^T A\|_2 = \sigma_{\max}^2 = \sigma_1^2 \dots \mathbf{2} \rightarrow$$

$$\mathbf{1} \ \& \ \mathbf{2} \rightarrow \|A\|_2^2 = \|A^T A\|_2.$$

(b) $\|A\|_F = \sqrt{\sigma_1^2 + \sigma_2^2 + \dots + \sigma_n^2}$, when $\sigma_1, \sigma_2, \dots, \sigma_n$ are the singular values of A .

$$\text{Since } \|A\|_F^2 = \text{trace}(A^T A) \text{ and } A = \bar{U}\Sigma V^T;$$

$$\|A\|_F^2 = \text{trace}(A^T A) = \text{trace}(V\Sigma^T \bar{U}\Sigma V^T)$$

$$= \text{trace}(V\Sigma^T \Sigma V^T)$$

Since two similar matrices have the same eigenvalues and the trace of a matrix is the sum of eigenvalues,

$$\begin{aligned} \|A\|_F^2 &= \text{trace}(V\Sigma^T \Sigma V^T) = \text{trace}(\Sigma^T \Sigma) \\ &= \sigma_1^2 + \sigma_2^2 + \dots + \sigma_n^2. \end{aligned}$$

(c) $\text{rank}(A^T A) = \text{rank}(A)$.

$$A = \bar{U}\Sigma V^T \quad A^T = V\Sigma\bar{U}^T$$

$$m \geq n. \quad A = \bar{U} \begin{pmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_n \\ 0 & \dots & \dots & 0 \\ 0 & \dots & \dots & 0 \end{pmatrix}$$

$$A^T A = V\Sigma^T \Sigma V^T$$

$$\Sigma^T \Sigma = \begin{pmatrix} \sigma_1^2 & & & \\ & \sigma_2^2 & & \\ & & \ddots & \\ & & & \sigma_n^2 \end{pmatrix}_{n \times n}$$

The # of nonzero singular values of A is equal to the # of nonzero singular values of $A^T A \rightarrow \text{rank}(A) = \text{rank}(A^T A)$.